Keck 2012, Differential Pointing

Rx0 Rx1 Rx2 Rx3 Rx4
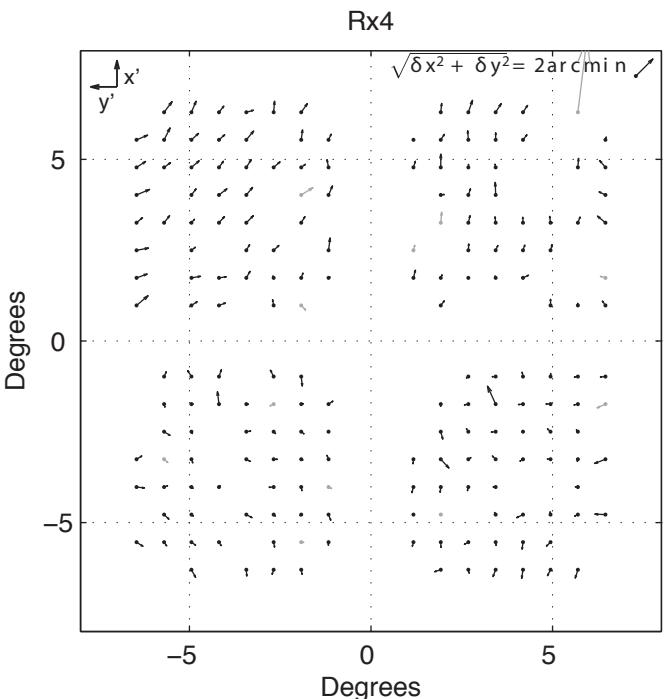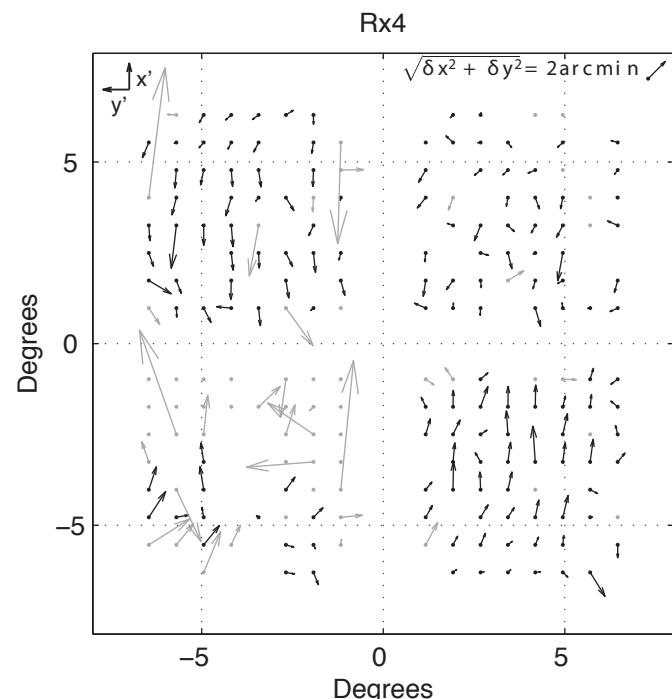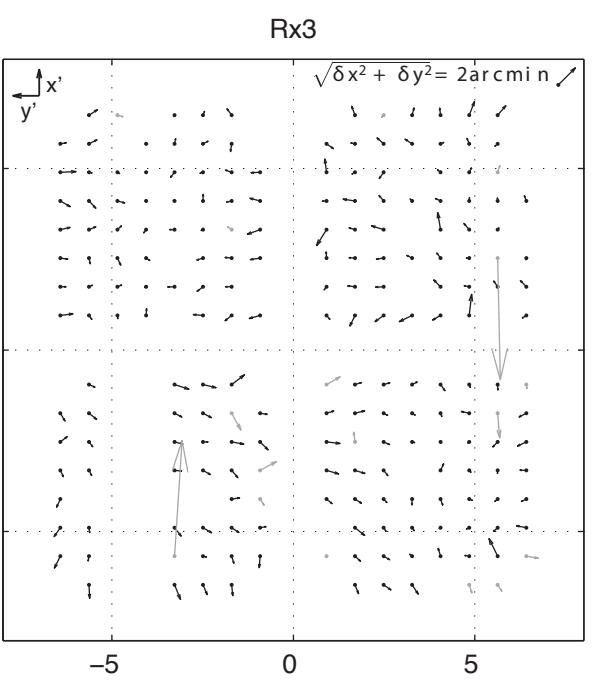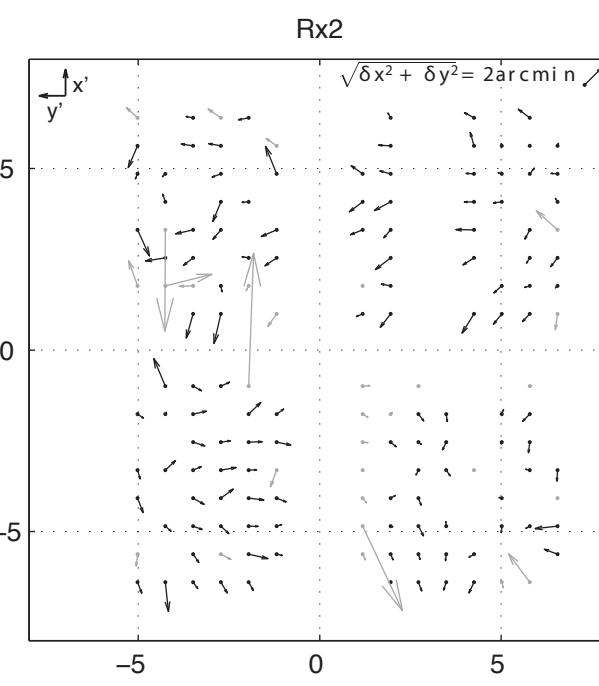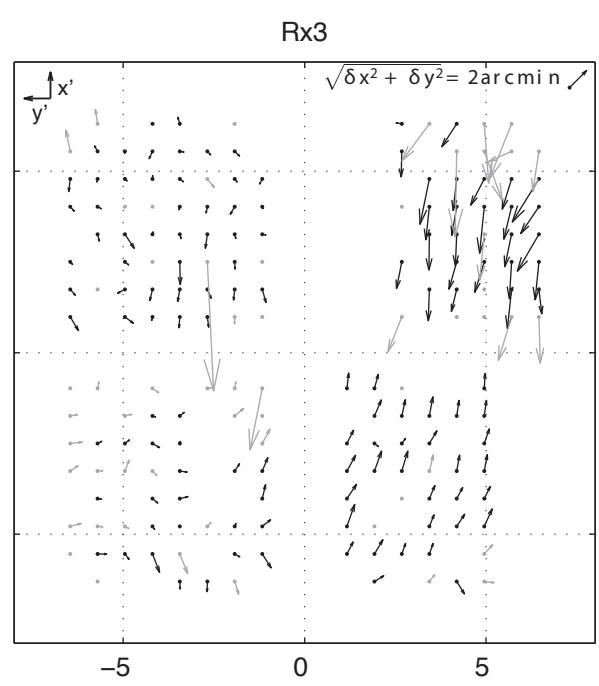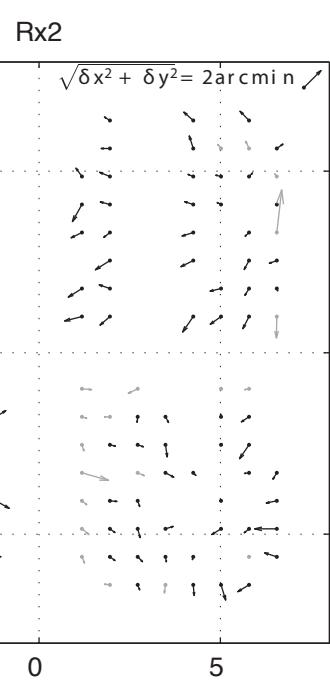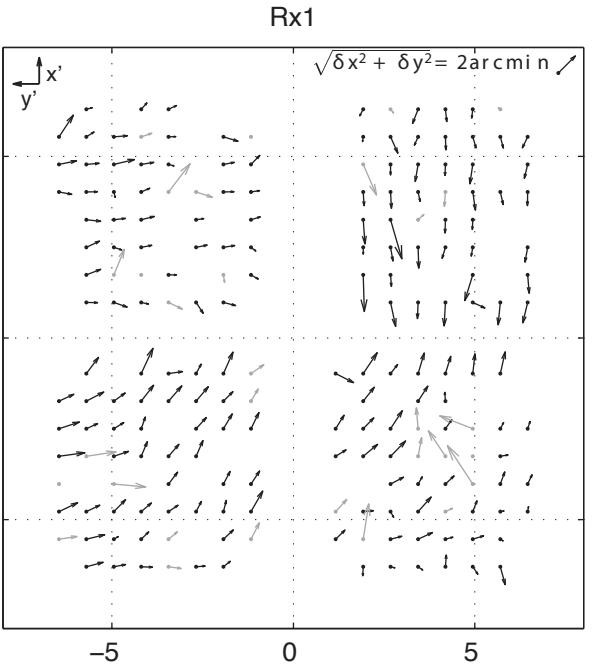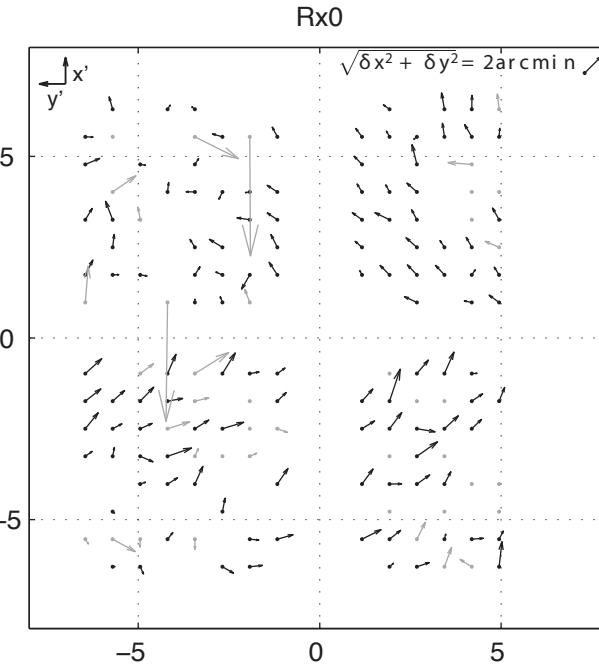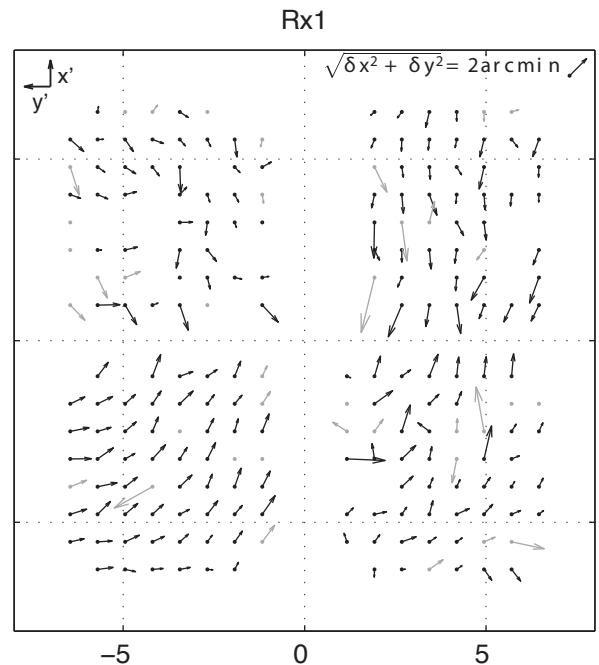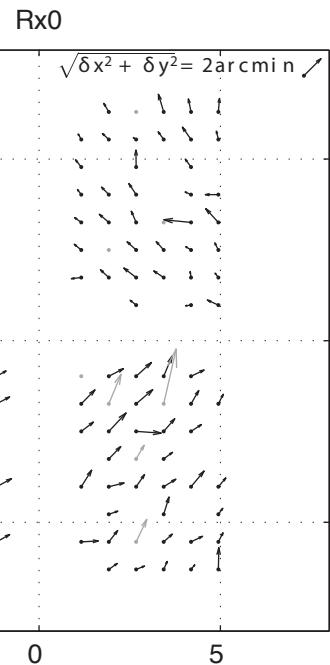
Keck 2013, Differential Pointing

Rx0 Rx1 Rx2 Rx3 Rx4

$\sqrt{\delta x^2 + \delta y^2} = 2\,arcmin$

Degrees